





A robotic solution for Cbrn Defence, dedicated to critical infrastructures

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CONTEXT, BACKGROUND

- 2002 first step
- 2010 end of project 1
- 2011 new consortium









THE OPERATIONAL CONCEPT

Inspection and reconnaissance:

Immediately,



first measurements and images.

- **Detection and measurement:** following a tactical decision.
- Neutralization: postponed action interacting with the source in order to neutralize





TOWARD A RANGE OF ROBOTS ?

Lightweight, around
1 kg, for inspection and
reconnaissance operations.
May be lost able.



- Medium weight, several tens of kilos, suitable for specialist missions
- Heavyweight, semi-automatic platform to follow one member or to support the Hazmat team





ON INCIDENT SCENE







FONCTIONAL APPROACH

Linked to the platform :

Geiger-Müller + Ex detectors

Plug and play system:

- Radioactive detectors
- Chem and Ex detectors
- HD + video Camera
- IR CAM
- Robotic arm
- Water high pressure gun
- Liquid and gaseous sampler







FONCTIONAL APPROACH





EVALUATION

2009, 2010, 2011,

- Global performance test
- Chlorine field test
- Rail hazmat test
- Underground parking test
- Metro terrorist attack test







EVALUATION SKILLS

- 7 evaluation domains, gathering 105 criteria 100,00%
- Easiness
- Roughness
- Transmissions
- Identification and Measurement
- Imaging
- Operations
- Logistics







CURRENT EVOLUTIONS

- Increase heat resistance,
- Improvement of the humanmachine interface,
- Optimized interoperability with other robotics appliances,
- Geographic localisation,
- Neutralization of LPG cylinders.







Energy and the Environment

Ralian National Agency for New Technologies,







Is there an European future for civil protection and defence robotic tools ?





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